



COURSE DESCRIPTION CARD - SYLLABUS

Course name

Automatics

Course

Field of study

Mechanical Engineering

Area of study (specialization)

Level of study

First-cycle studies

Form of study

full-time

Year/Semester

2/4

Profile of study

general academic

Course offered in

Polish

Requirements

compulsory

Number of hours

Lecture

15

Laboratory classes

15

Other (e.g. online)

Tutorials

15

Projects/seminars

Number of credit points

4

Lecturers

Responsible for the course/lecturer:

Tomasz Bartkowiak, PhD

Responsible for the course/lecturer:

email: tomasz.bartkowiak@put.poznan.pl

Faculty of Mechanical Engineering

Institute of Mechanical Technology

ul. Piotrowo 3, 60-965 Poznań

Prerequisites

Basic knowledge of mathematics including: set theory, algebra of complex number, differential equations, Boolean algebra and of other areas of education in the field of study. Systematized theoretical knowledge in the field of study.

Basic command of complex and logical variables and sets, solving simple differential equations, describing basic physical phenomena in mechanics. Ability to use literature (acquire knowledge from the indicated sources) and the Internet.

Understanding the need for lifelong learning. Understanding the social effects of engineering activities. Understanding the need for team collaboration.



Course objective

Understanding the components of control systems and principles of automation including basic concepts and static and dynamic properties of elements and linear and nonlinear control systems, definitions and selection of controllers, automation of complex systems.

Course-related learning outcomes

Knowledge

The student knows what an automation system is, knows the difference between an open- and closed-loop control, knows the basic concepts of automation and knows the tasks of automation.

The student knows what are Boolean functions, combinational and sequential systems, the phenomenon of hazard in on-off control systems.

The student knows the methods of implementing Boolean functions in the form of contact elements and logic gates as well as on-off control of fluid systems.

The student knows what the transfer function is and knows the unit-step response of basic linear automation systems.

The student knows what the definitions and how to determine the frequency characteristics of automation components. Knows the basic concept and methods of system stability.

The student knows the definitions and how classic controllers are built, knows the problem of stability determination.

The student knows the structure of comprehensive automation systems and knows, in general, what the production control is.

Skills

The student is able to describe the basic components of linear control systems, including the transfer characteristics and examples.

The student knows how to perform a given combination and sequential binary function using contact, contactless and fluid systems in a hazard-free manner.

The student knows how to determine the frequency characteristics of basic elements and determine the stability of a simple automation system.

The student is able to determine the transfer function of any connected basic elements of control system.

The student can describe the operation of the PID controller and determine the stability of a simple automation system.



The student knows how to define the tasks of a comprehensive automation system and production control.

Social competences

The student understands the need to track currently available solutions in the field of automation and control systems.

Methods for verifying learning outcomes and assessment criteria

Learning outcomes presented above are verified as follows:

Tutorials: Completion of exercises, based on preparation for classes and the test. The test, in a written form, with a minimum of three open problems to solve. Positive grade >50% of correct answers.

Laboratory: Completion of the laboratory exercises, based on the preparation for classes and reports on completed classes. Credit based on the correct execution of the exercises and a report on each laboratory exercise according to the instructions of the laboratory teacher. Short entrance tests before exercise. In order to get a credit for the laboratories, all exercises must be passed (positive assessment of the introductory test and reports).

Lecture: Exam in the form of a written test, within the scope of lectures, consisting of a minimum of 10 questions. Multiple choice test with a minimum of 4 possible answers to each question. Positive grade >50% of correct answers.

Programme content

- Basic concepts in Boolean algebra and control theory
- Analysis and synthesis of on-off control systems
- Analysis and synthesis of sequential automation systems
- Hazard in switching systems
- Elements and systems of automation and machine automation
- Static and dynamic properties of elements and methods of their determination
- Linear and nonlinear automation systems
- Regulation systems and selection of regulators

Teaching methods

Lecture: a lecture supported by a multimedia presentation containing the discussed program content.

Tutorials: problem solving, discussion.

Laboratory: practical exercises, teamwork.

Bibliography



Basic

1. Żelazny M., Podstawy automatyki, PWN, 1976
2. Horla D., Podstawy automatyki – ćwiczenia rachunkowe, WPP, 2008
3. Traczyk W., Układy cyfrowe automatyki, WNT, 1974

Additional

1. Mikulski A., Elementy przekaźnikowych urządzeń automatyki, WKŁ, 1970
2. Kindler H., Buchta H., Wilfert H., Zadania z techniki regulacji automatycznej, WNT, 1971
3. Urbaniak A., Podstawy automatyki, WPP, 2001
4. Kostro J., Elementy, urządzenia i układy automatyzacji, WSiP, 1993
5. Kosmol J., Automatykacja obrabiarek i obróbki skrawaniem, WNT, 1995

Breakdown of average student's workload

	Hours	ECTS
Total workload	100	4,0
Classes requiring direct contact with the teacher	60	2,0
Student's own work (literature studies, preparation for laboratory classes/tutorials, preparation for tests/exam preparation) ¹	40	2,0

¹ delete or add other activities as appropriate